

OPTIMALLY LEARNING SOCIAL NETWORKS WITH ACTIVATIONS AND SUPPRESSIONS

ALT 2008

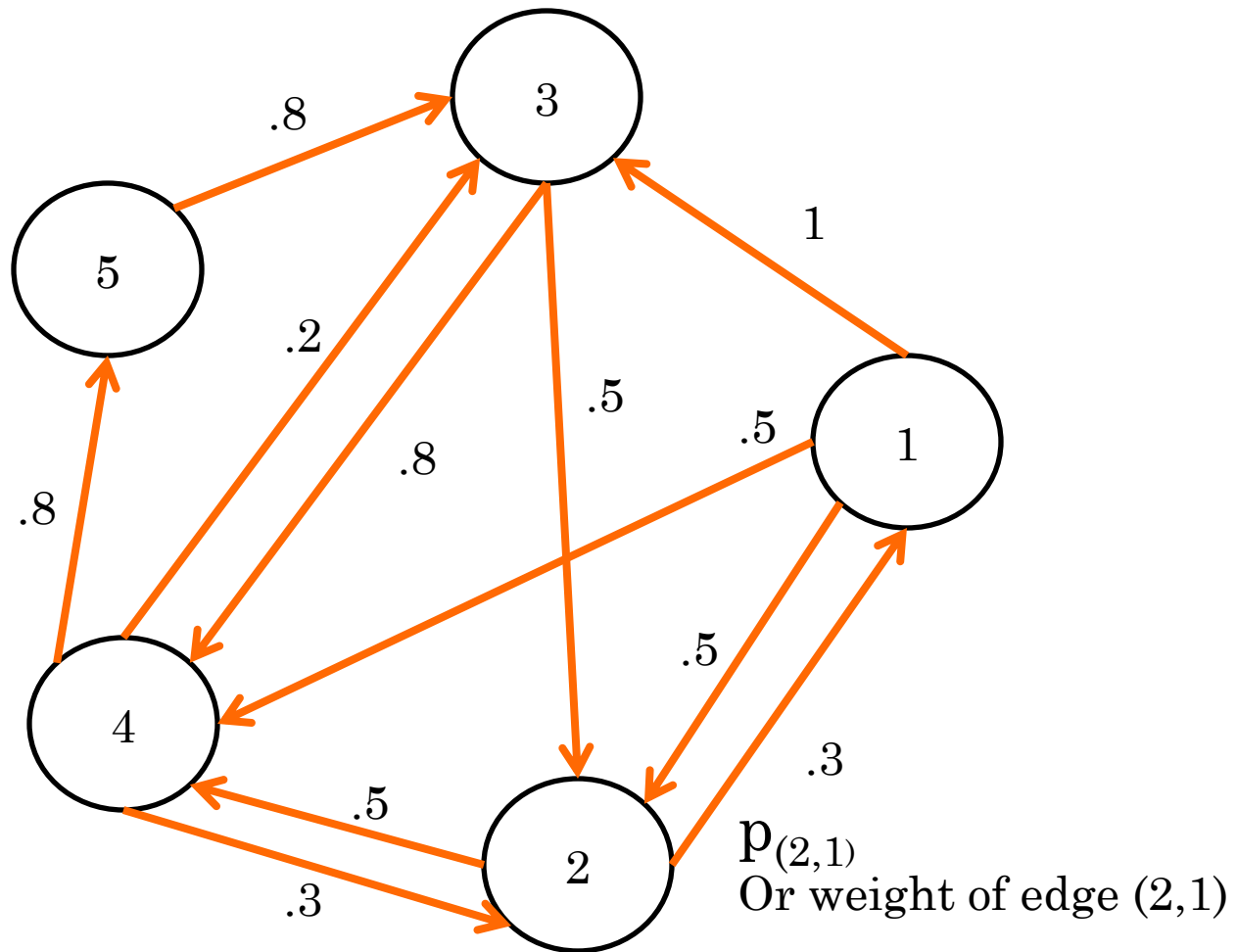
James Aspnes, Dana Angluin, Lev Reyzin
Yale University

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TALK OUTLINE

- Independent Cascade Social Networks (SNs)
- Introduce Value Injection Queries (VIQs) on SNs
 - VIQs override the values of node (or gates in the case of circuits)
 - These were introduced by [AACW \(STOC '06\)](#), extended in [AACR \(COLT '07\)](#) and [AACER \(COLT '08\)](#)
- Show **lower bound** for learning SNs with VIQs
- Give an idea of the **algorithm for learning** SNs
- Other results
 - Approximation algorithm
 - Special case of trees
 - Exponential attenuation of paths

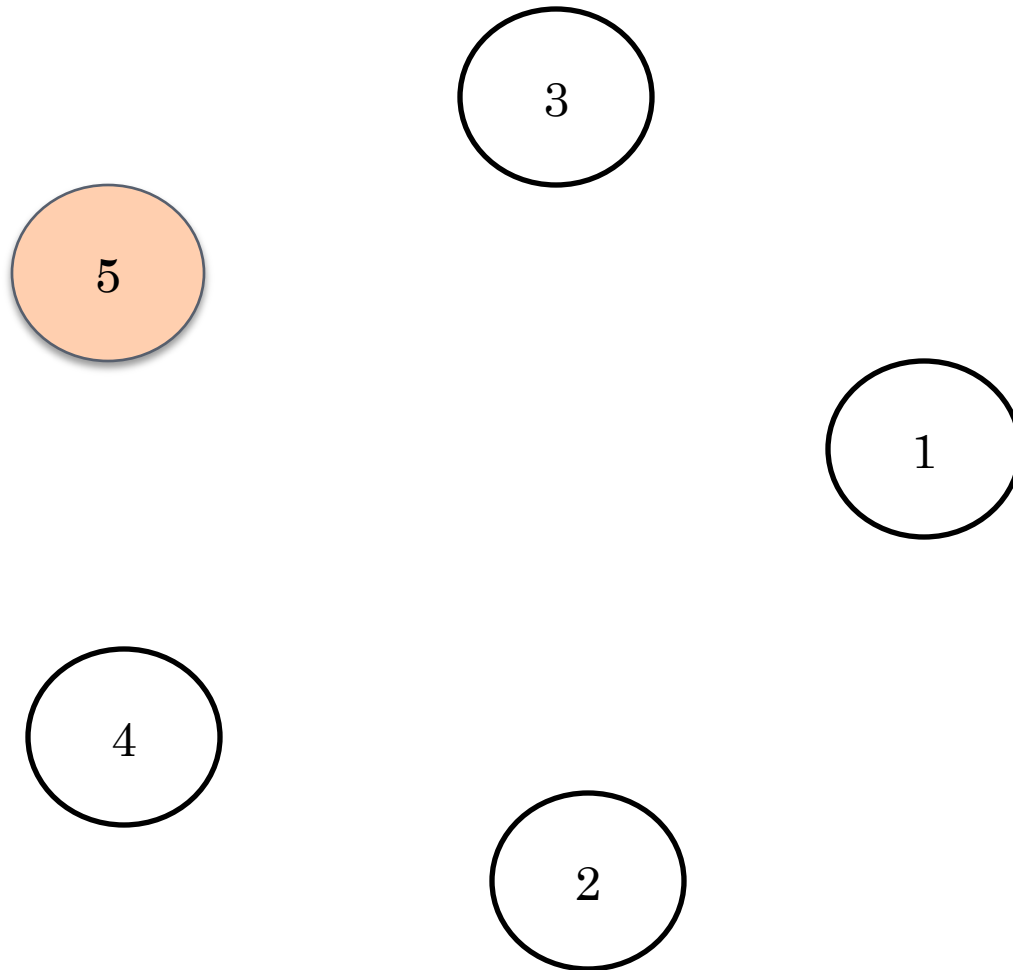
INDEPENDENT CASCADE SOCIAL NETWORKS



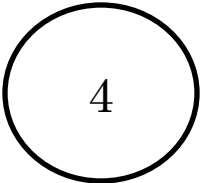
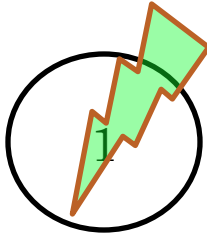
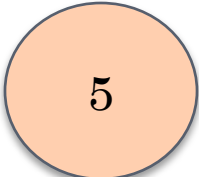
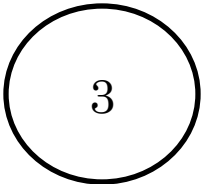
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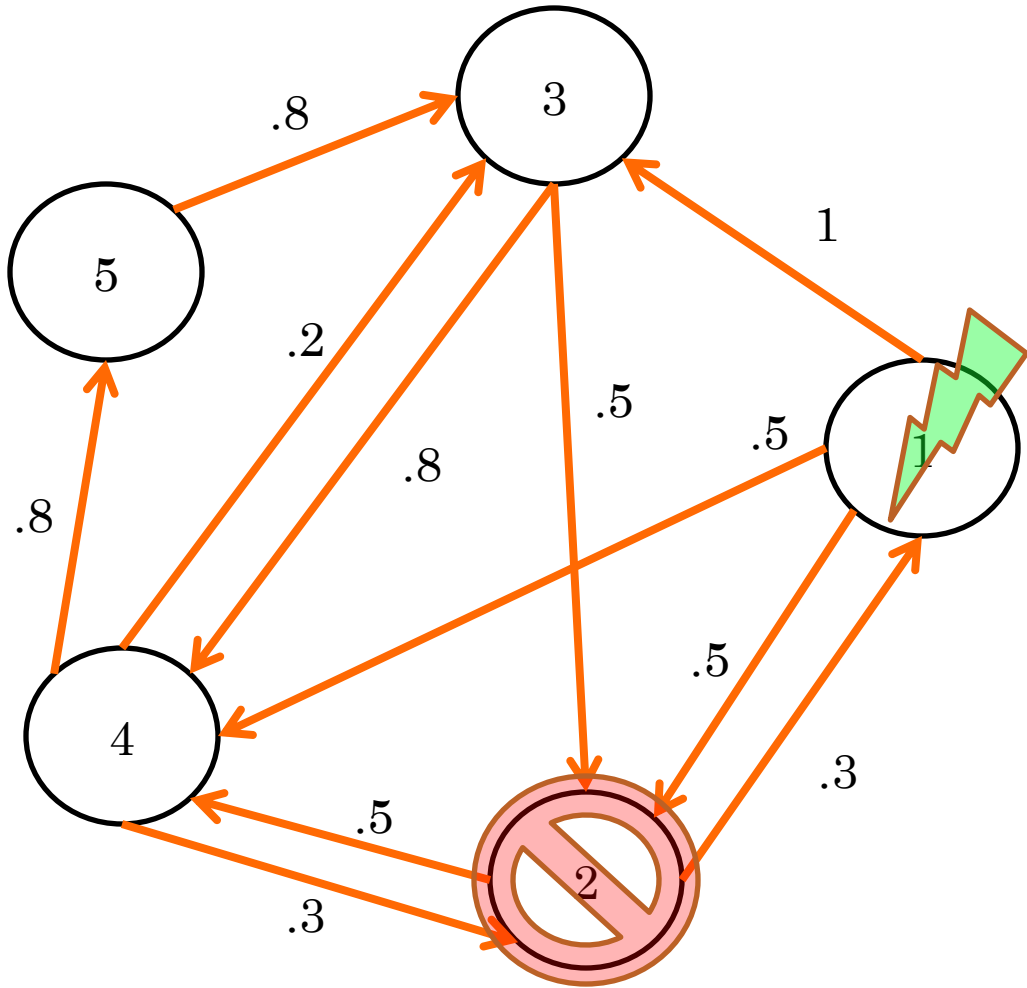
WHAT THE LEARNER SEES



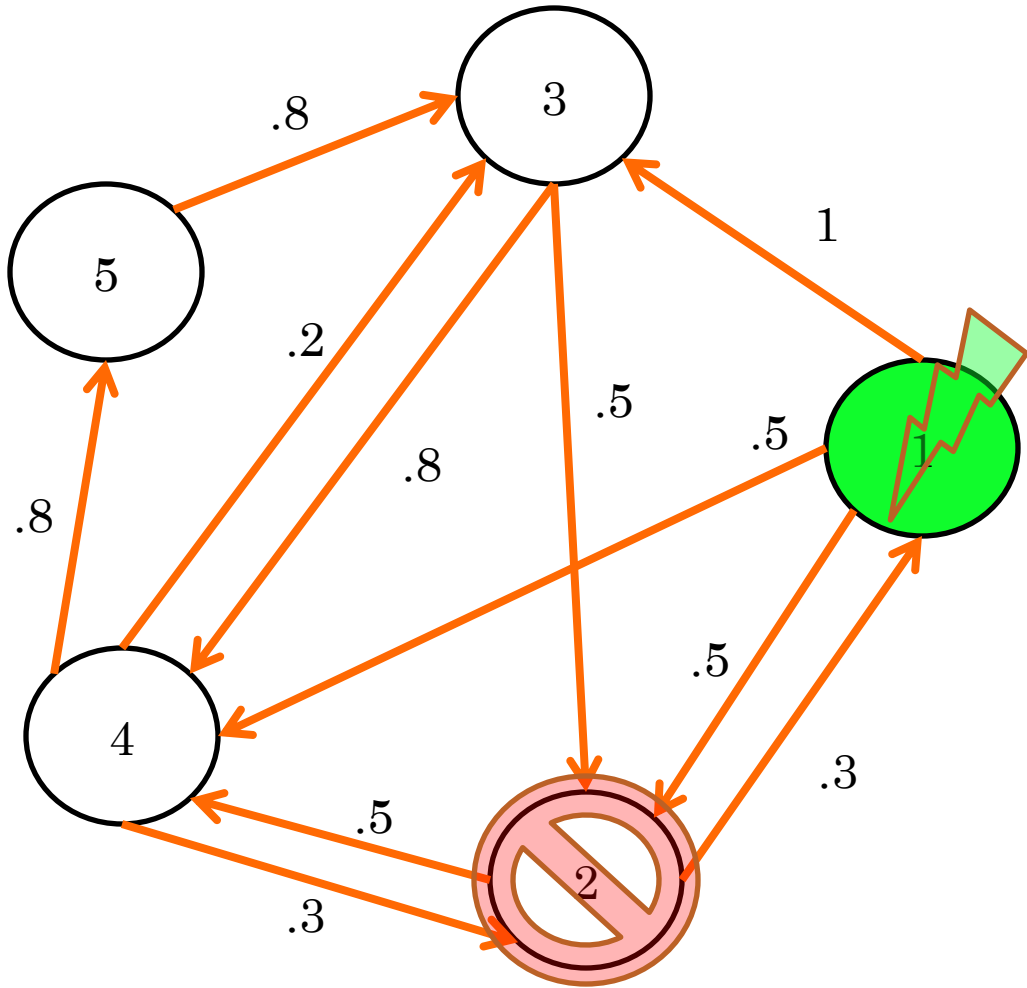
ACTIVATIONS AND SUPPRESSIONS



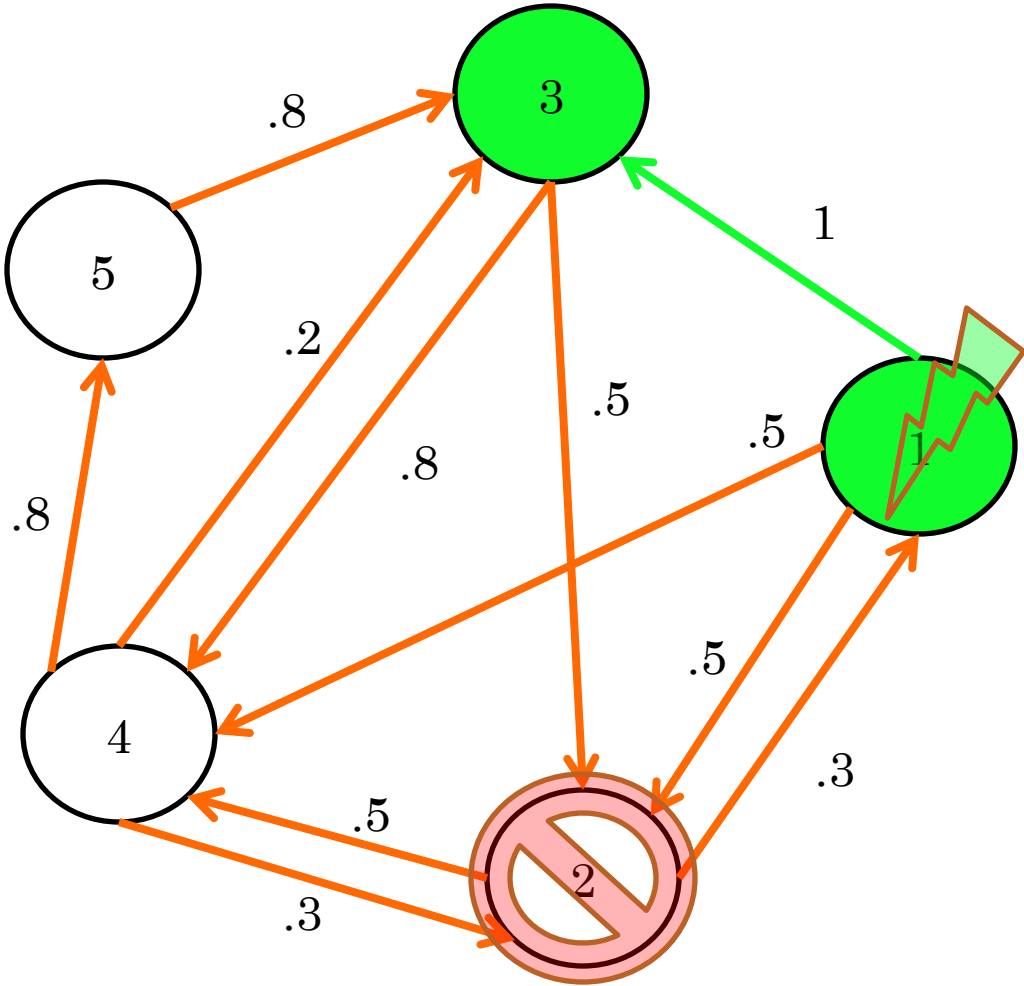
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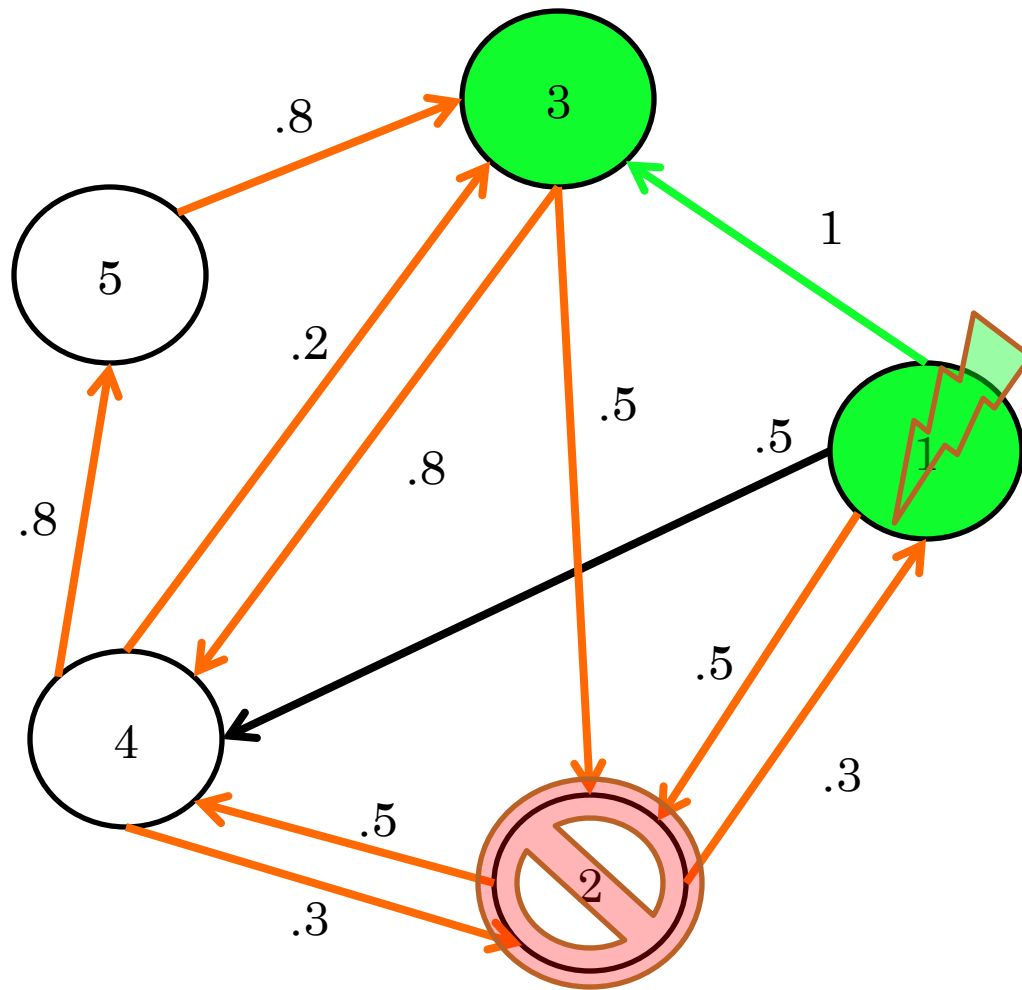
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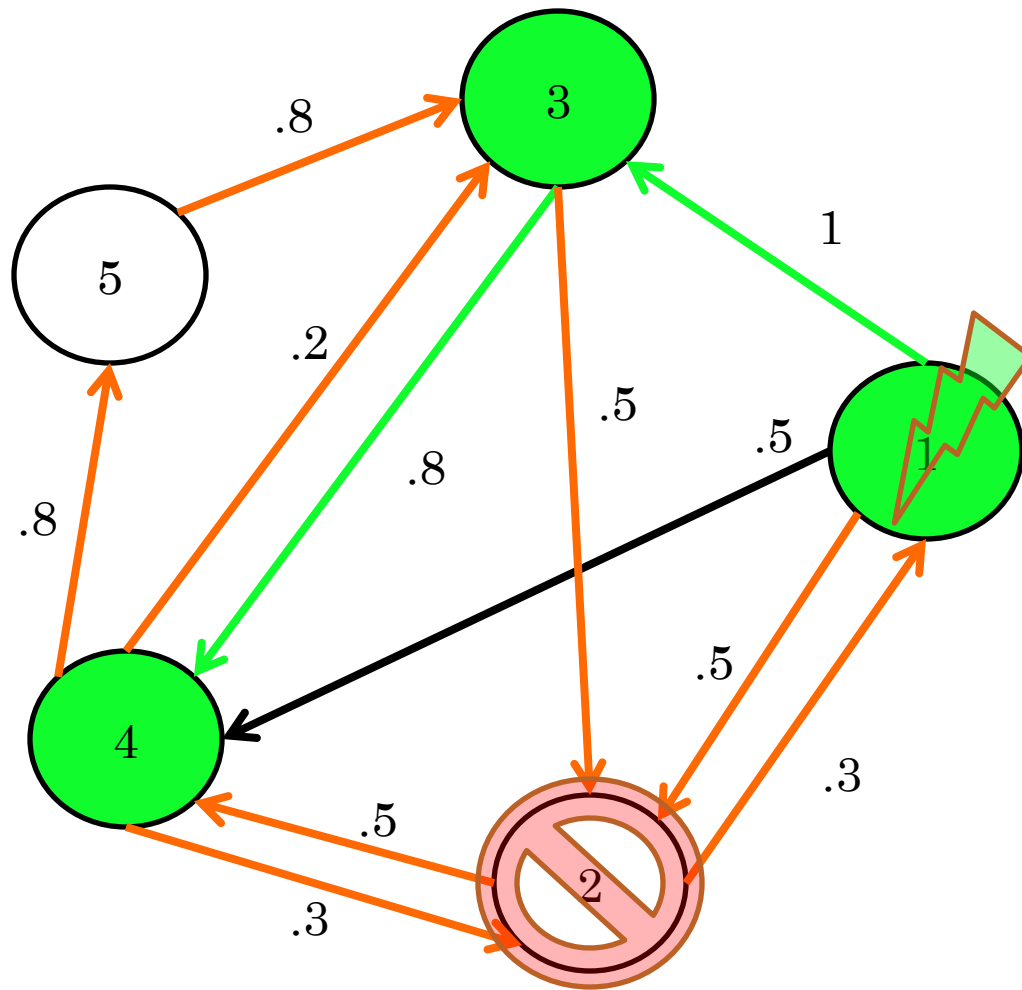
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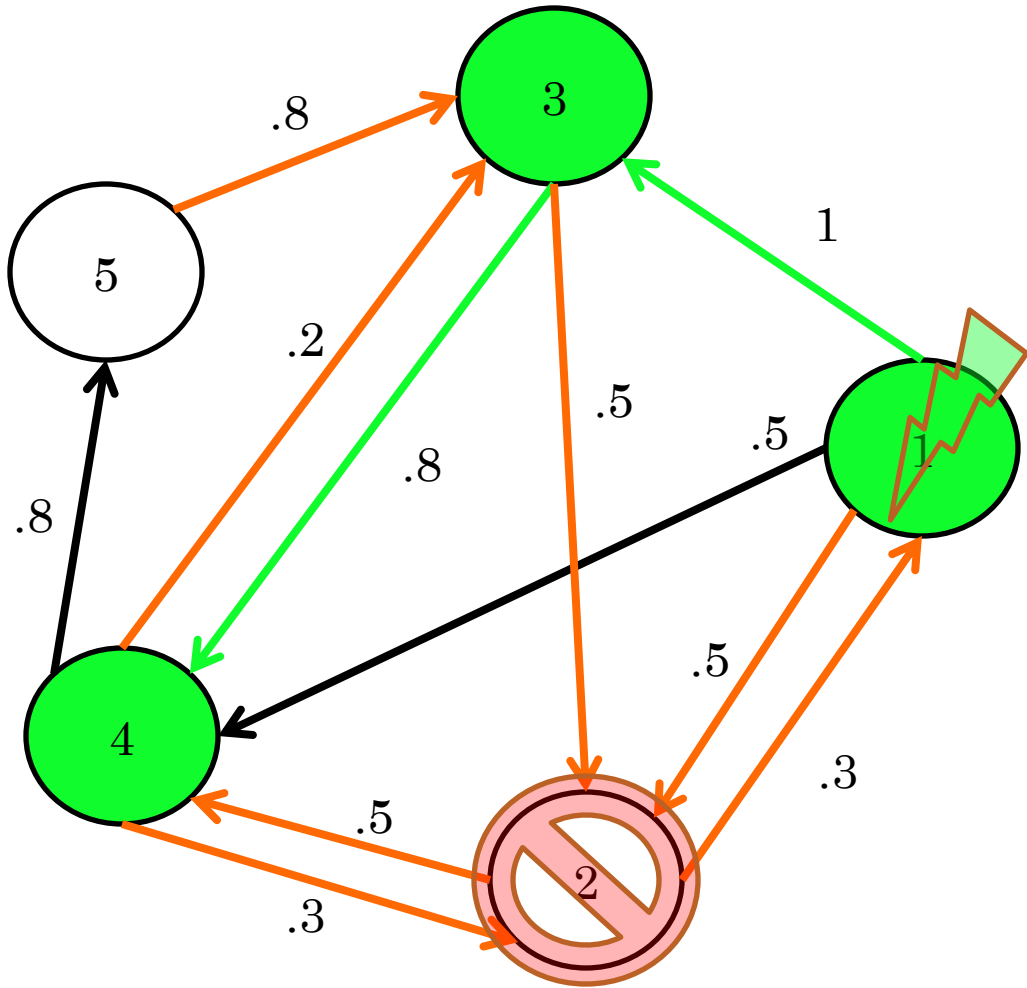
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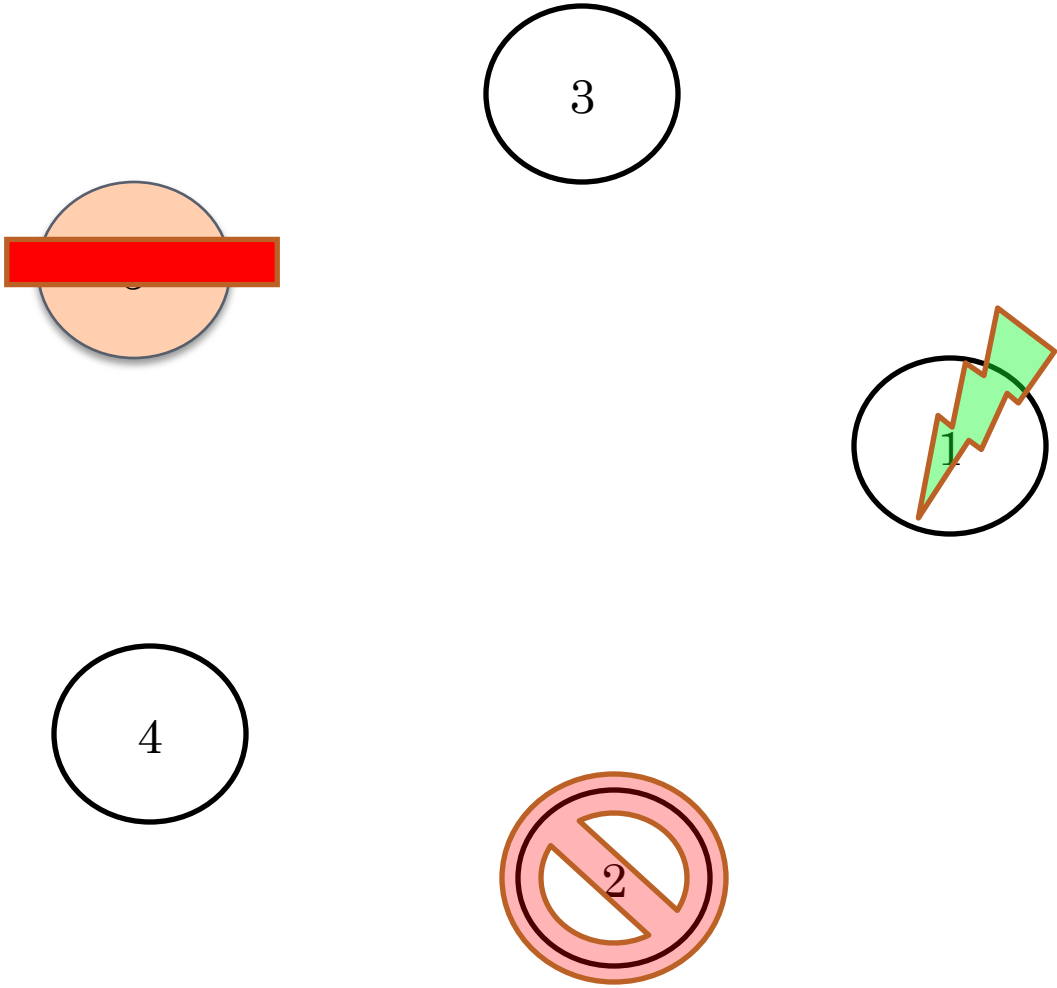
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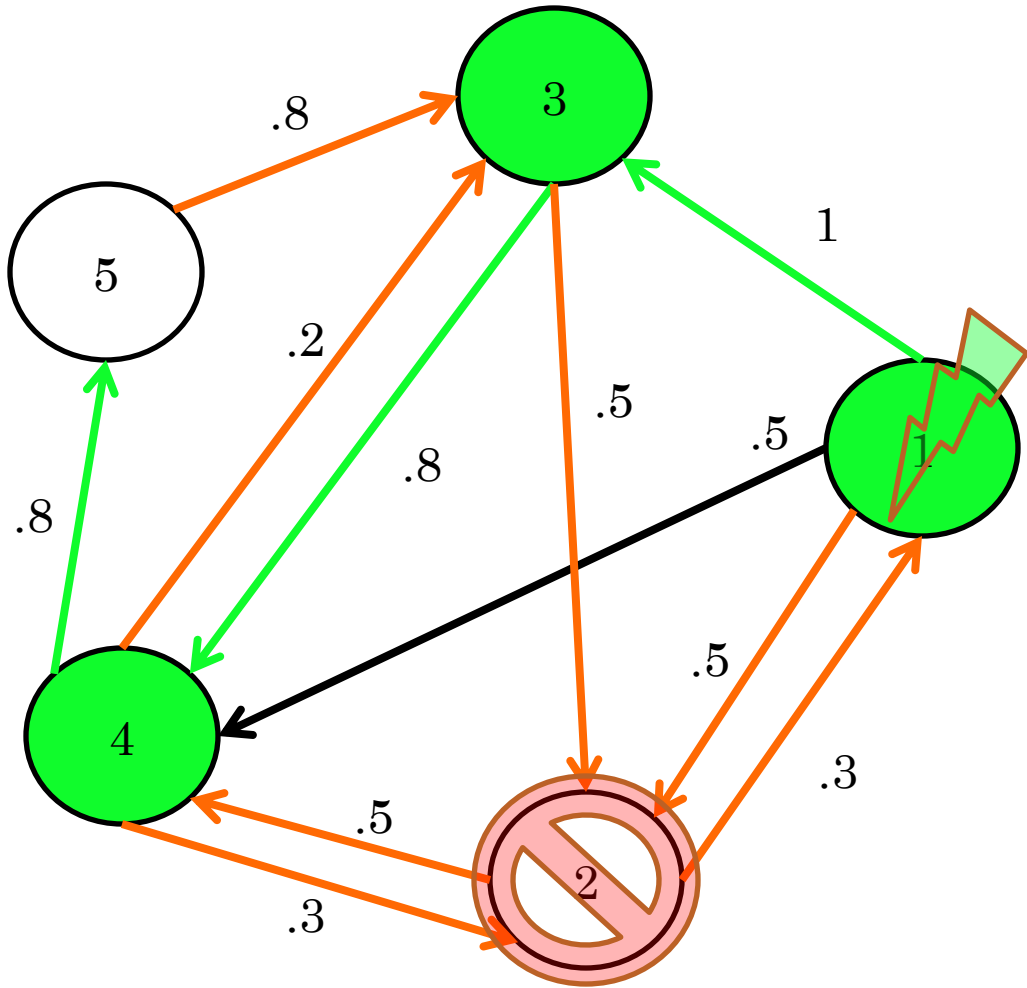
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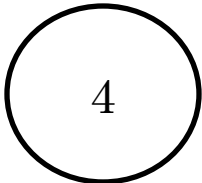
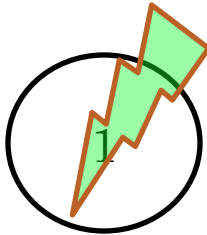
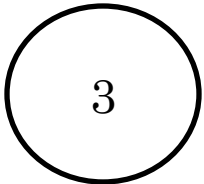
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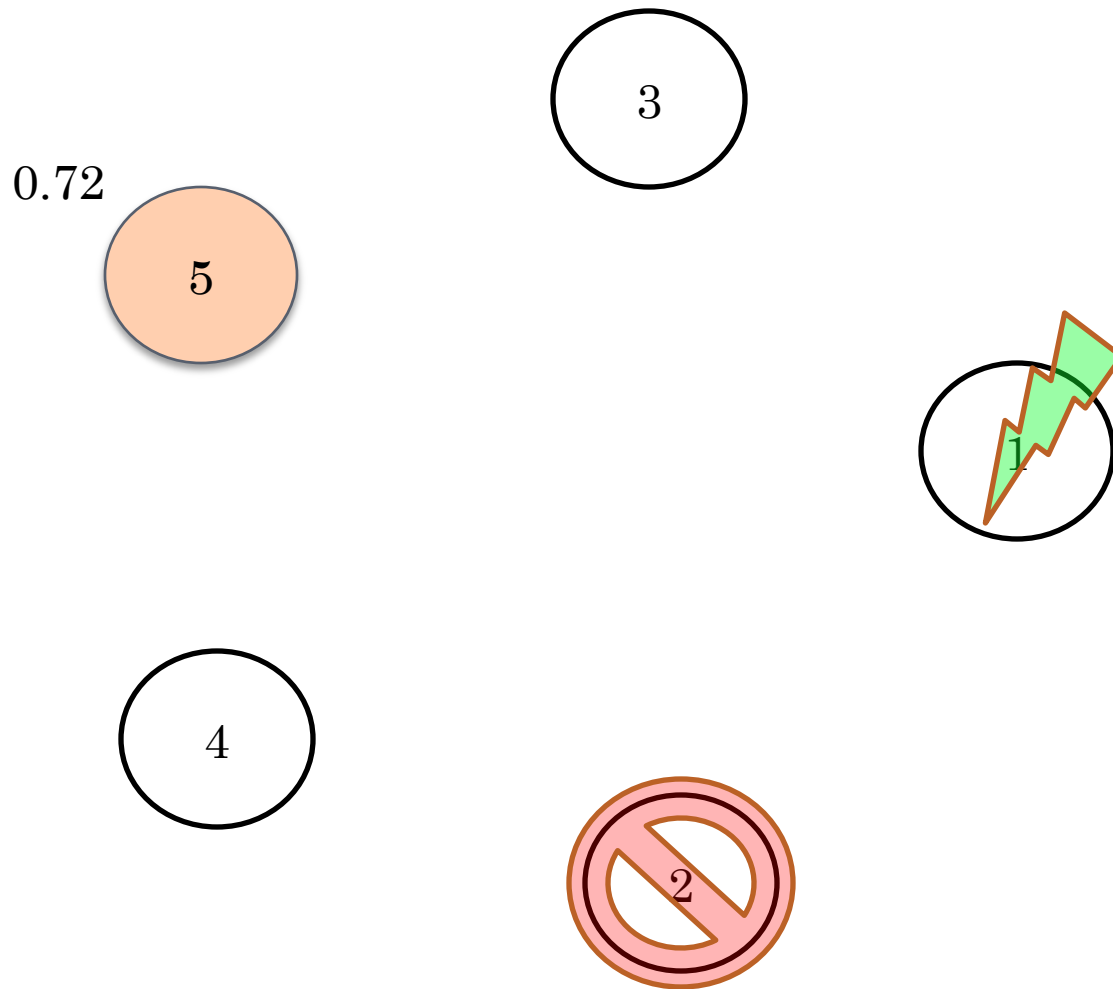
ACTIVATIONS AND SUPPRESSIONS



ACTIVATIONS AND SUPPRESSIONS



EXACT VALUE INJECTION QUERIES



THE LEARNING TASK

- Two social networks S and S' are **behaviorally equivalent** if for any experiment e , $S(e) = S'(e)$
- Give access to a hidden social network S^* , **the learning problem is** to find a social network S behaviorally equivalent to S^* using value injection queries.

THE PERCOLATION MODEL

Given a network S and a VIQ

- All edges entering or leaving a suppressed node are automatically “closed.”
- Each remaining edge (u,v) is “open” with probability $p_{(u,v)}$ and “closed” with probability $(1 - p_{(u,v)})$
- The result of a VIQ is the probability there is a path from a fired node to the output via open edges in S

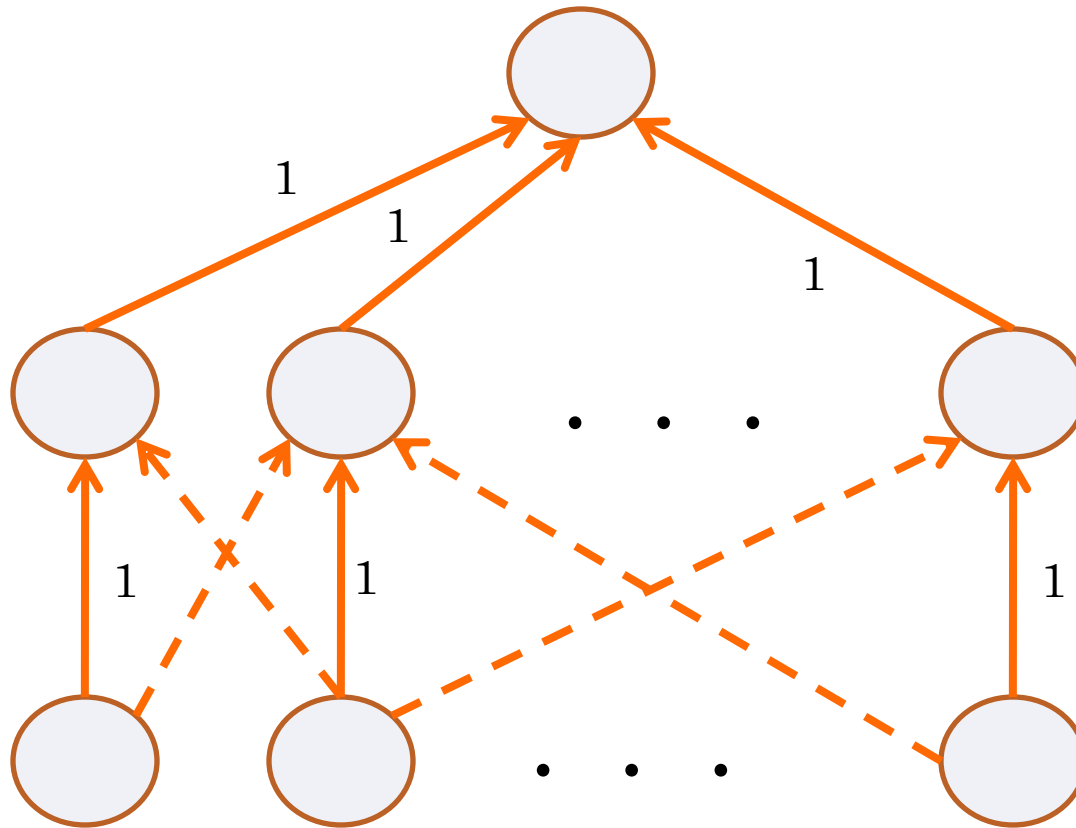
DISCOVERABLE EDGES

- Let S be a social network and S' be another social network that differs from S only in edge (u,v) .
- We say edge (u,v) is **discoverable** if there is an experiment e such that $S(e) \neq S'(e)$.
- We can view the learning problem as having to find all discoverable edges.

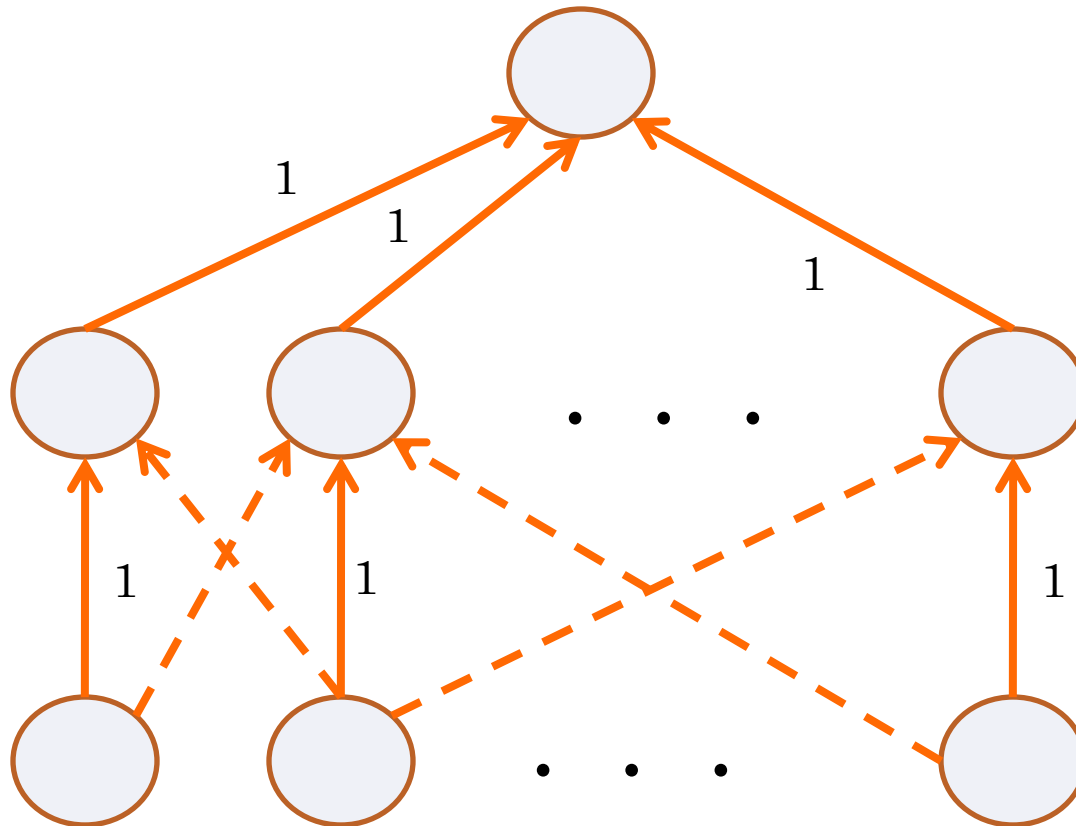
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A LOWER BOUND

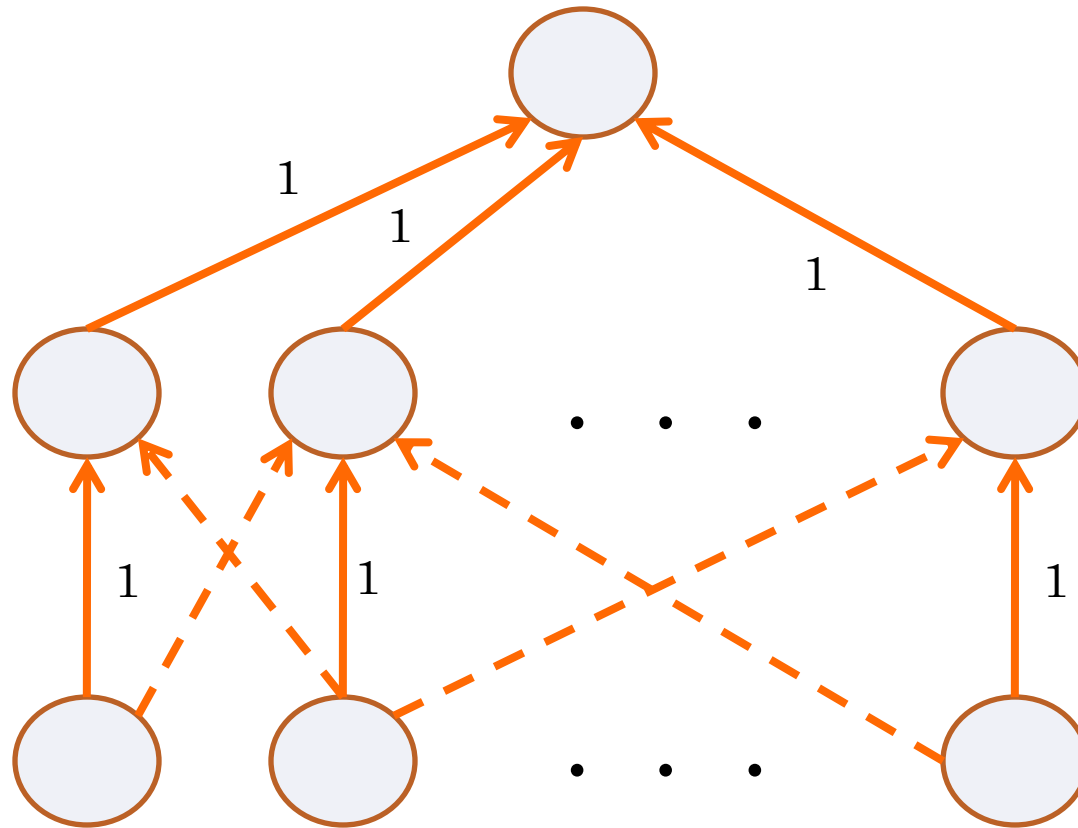


A LOWER BOUND



All queries give 1-bit answers

A LOWER BOUND



$2^{\Omega(n^2)}$ such graphs, $\Omega(n^2)$ l.b.

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FIRST SOME DEFINITIONS

- The **depth** of a node is its distance to the root
- An **Up edge** is an edge from a node of larger depth to a node of smaller depth
- A **Level edge** is an edge between two nodes of same depth
- A **Down edge** is an edge from a node at smaller depth to a node at higher depth
- A **leveled graph** of a social network is the graph of Up edges

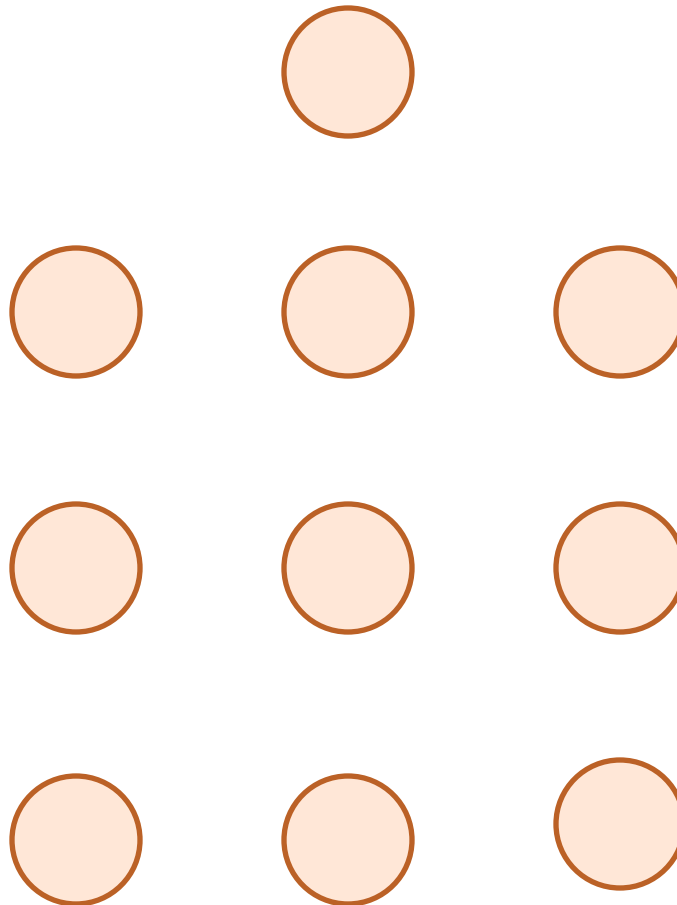
EXCITATION PATHS

- An **excitation path** for a node n is a VIQ in which a subset of the free agents form a simple directed path from n to the output. All agents not on the path with inputs into the path are suppressed.
- We also have a **shortest excitation path**

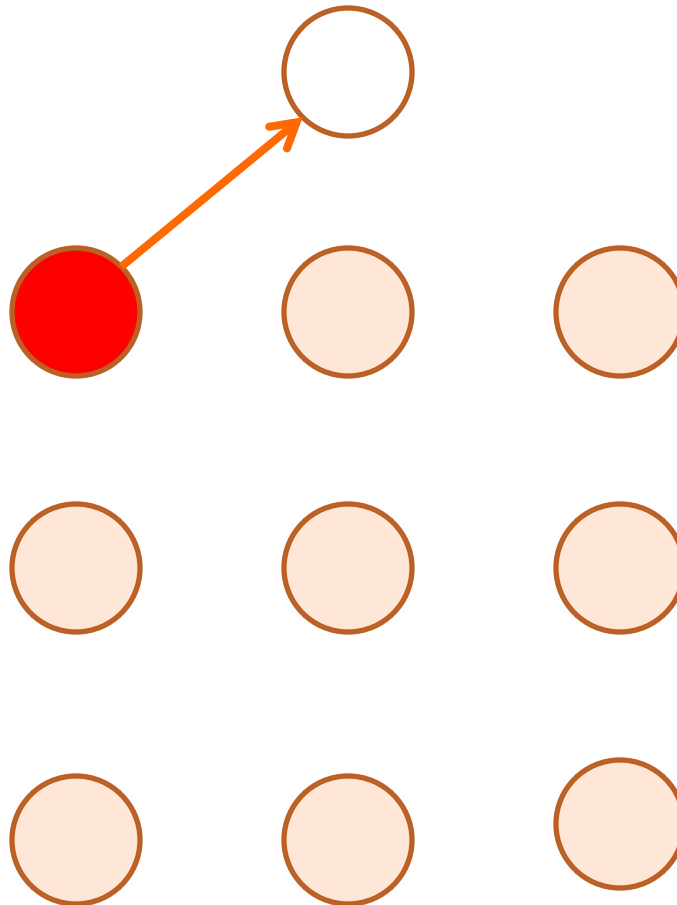
THE LEARNING ALGORITHM FOR NETWORKS WITHOUT 1 EDGES

- First **Find-Up-Edges** to learn the leveled graph of S
- For each level, **Find-Level-Edges**
- For each level, bottom-down, **Find-Down-Edges**

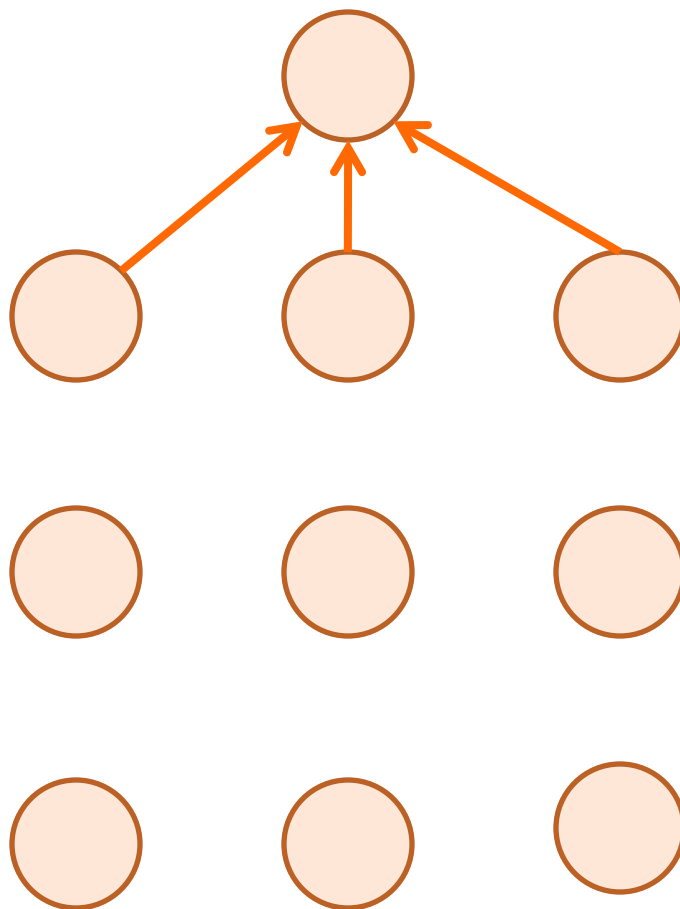
FIND-UP-EDGES



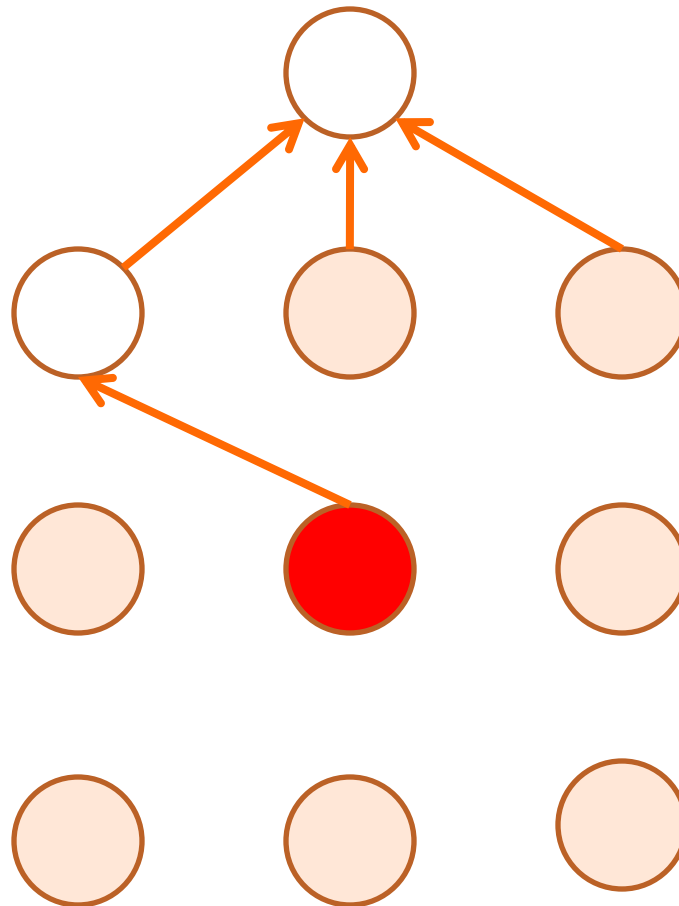
FIND-UP-EDGES



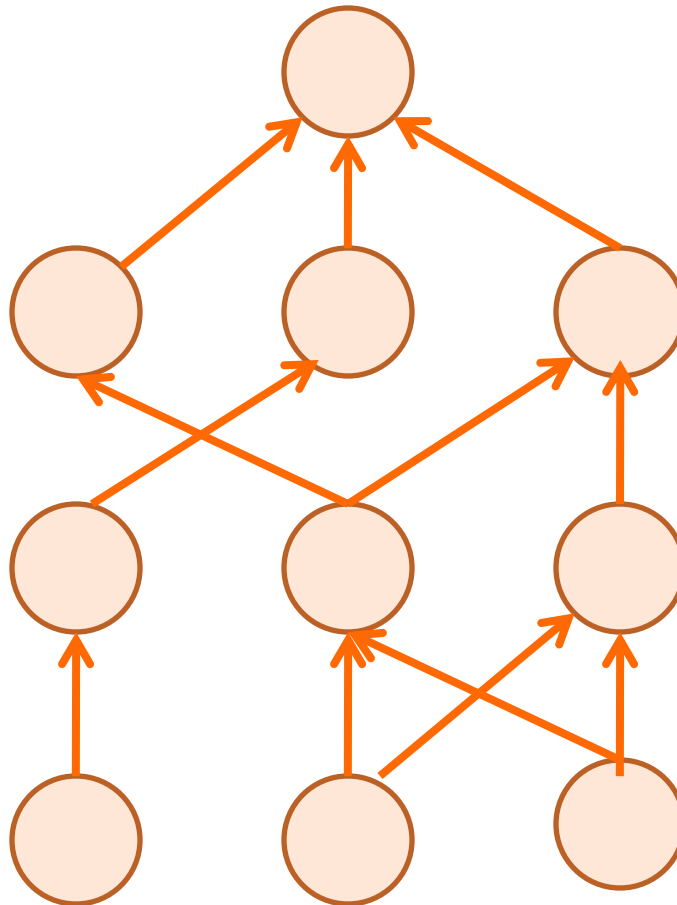
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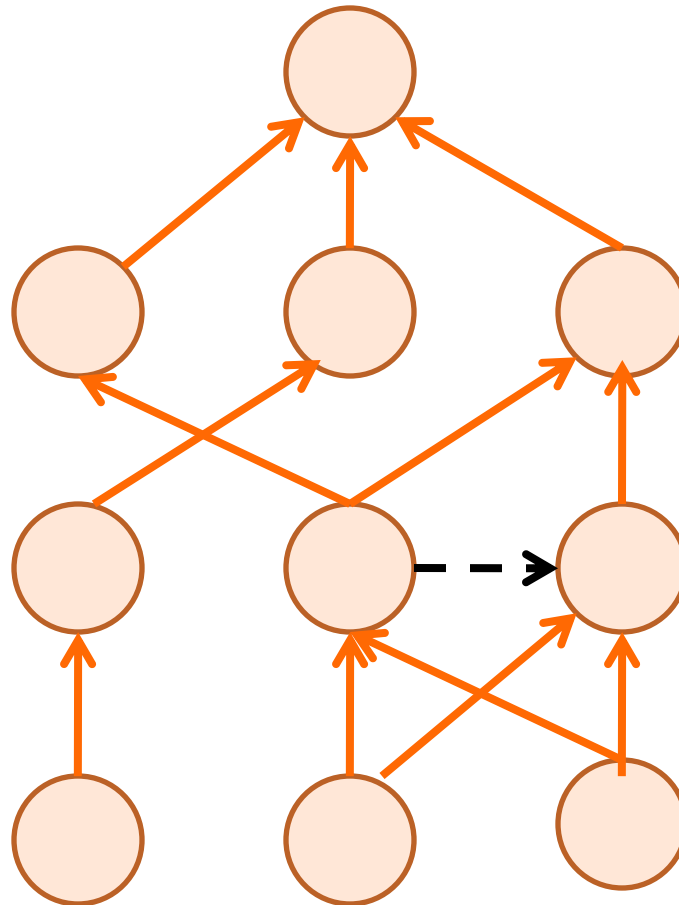
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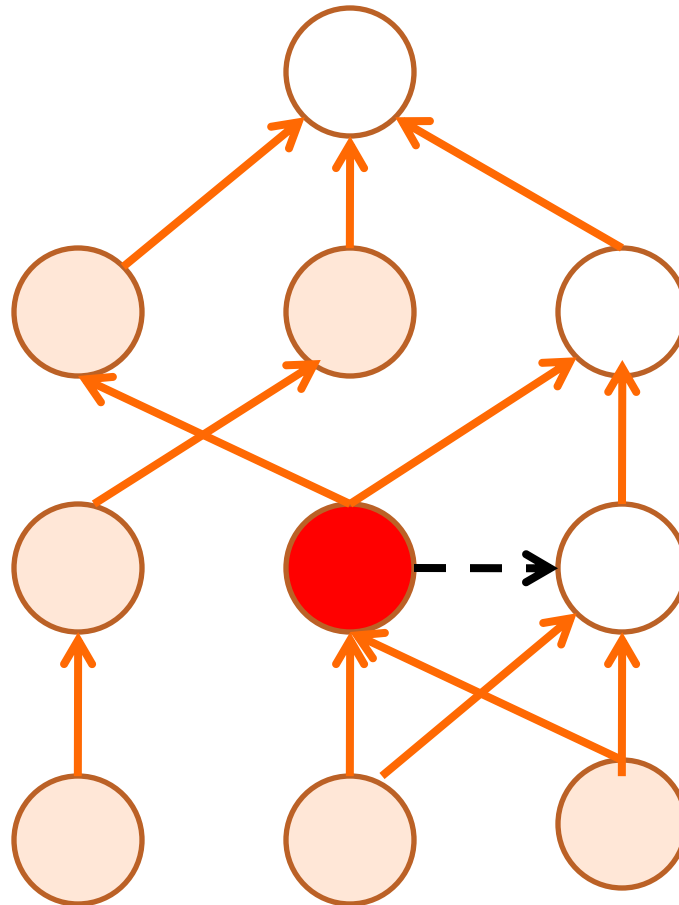
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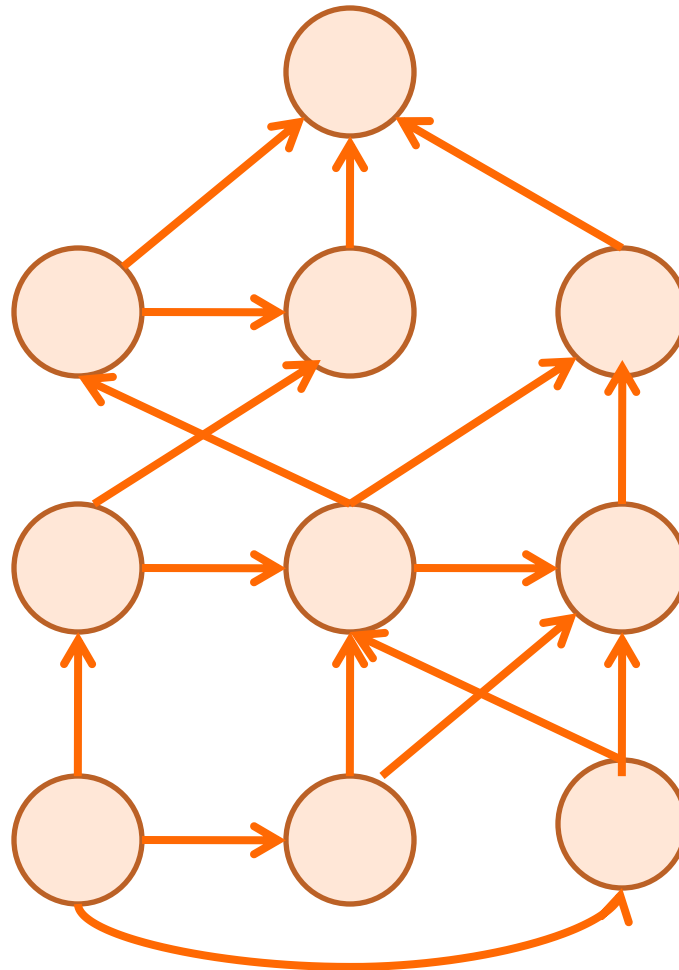
FIND-LEVEL-EDGES



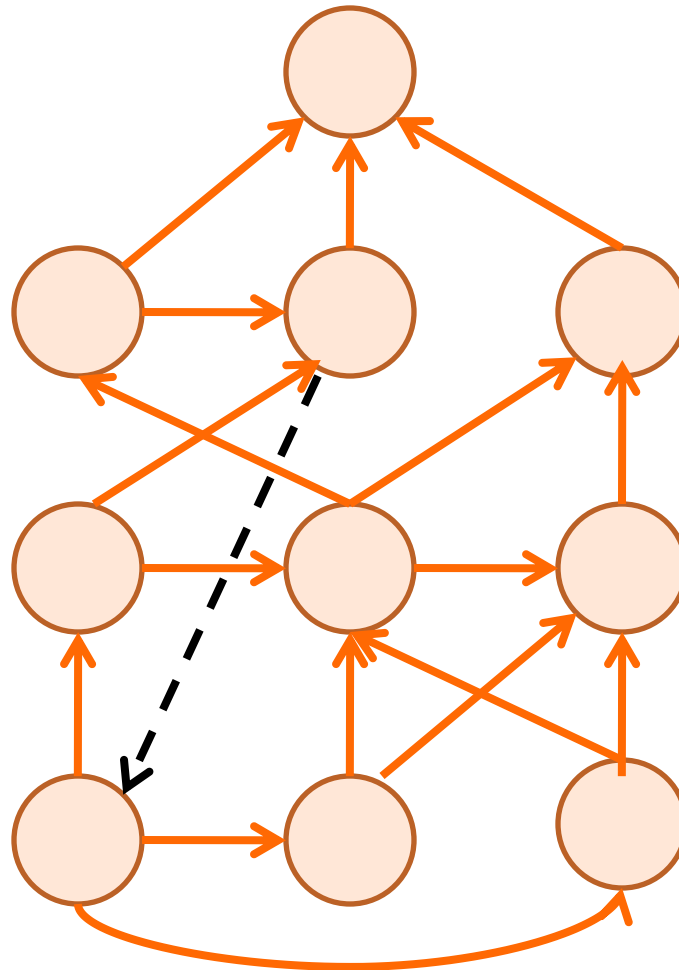
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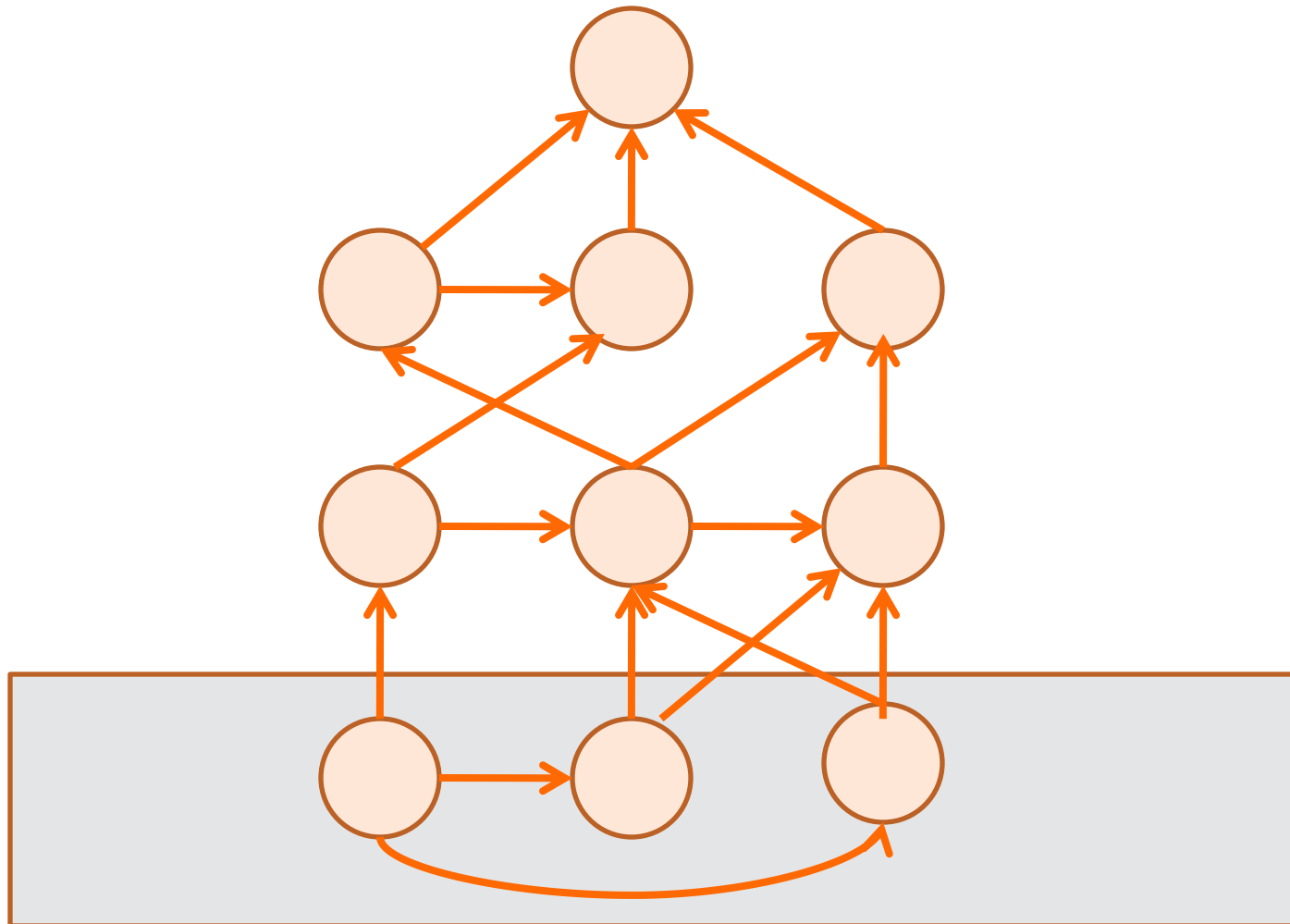
FIND-LEVEL-EDGES



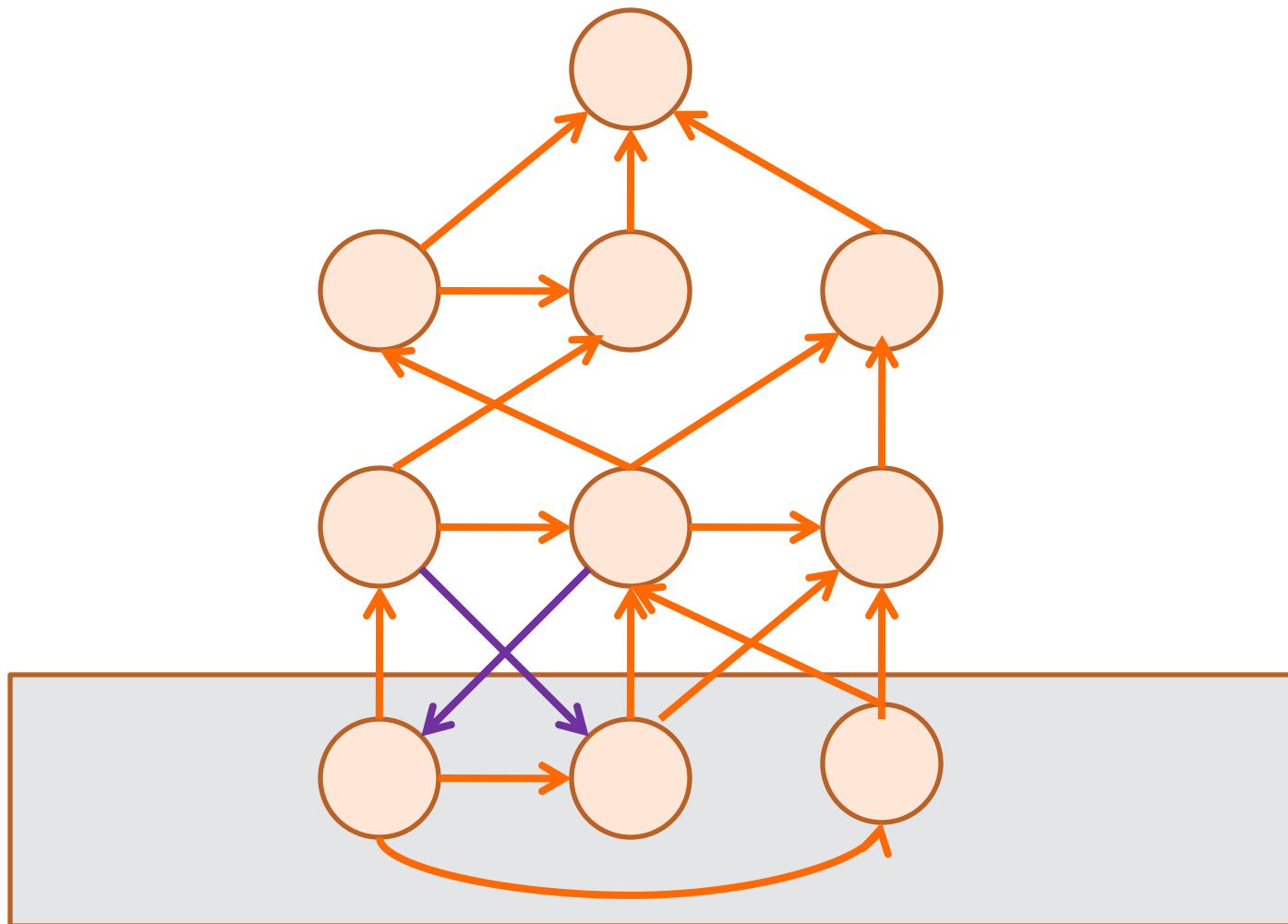
FIND-DOWN-EDGES



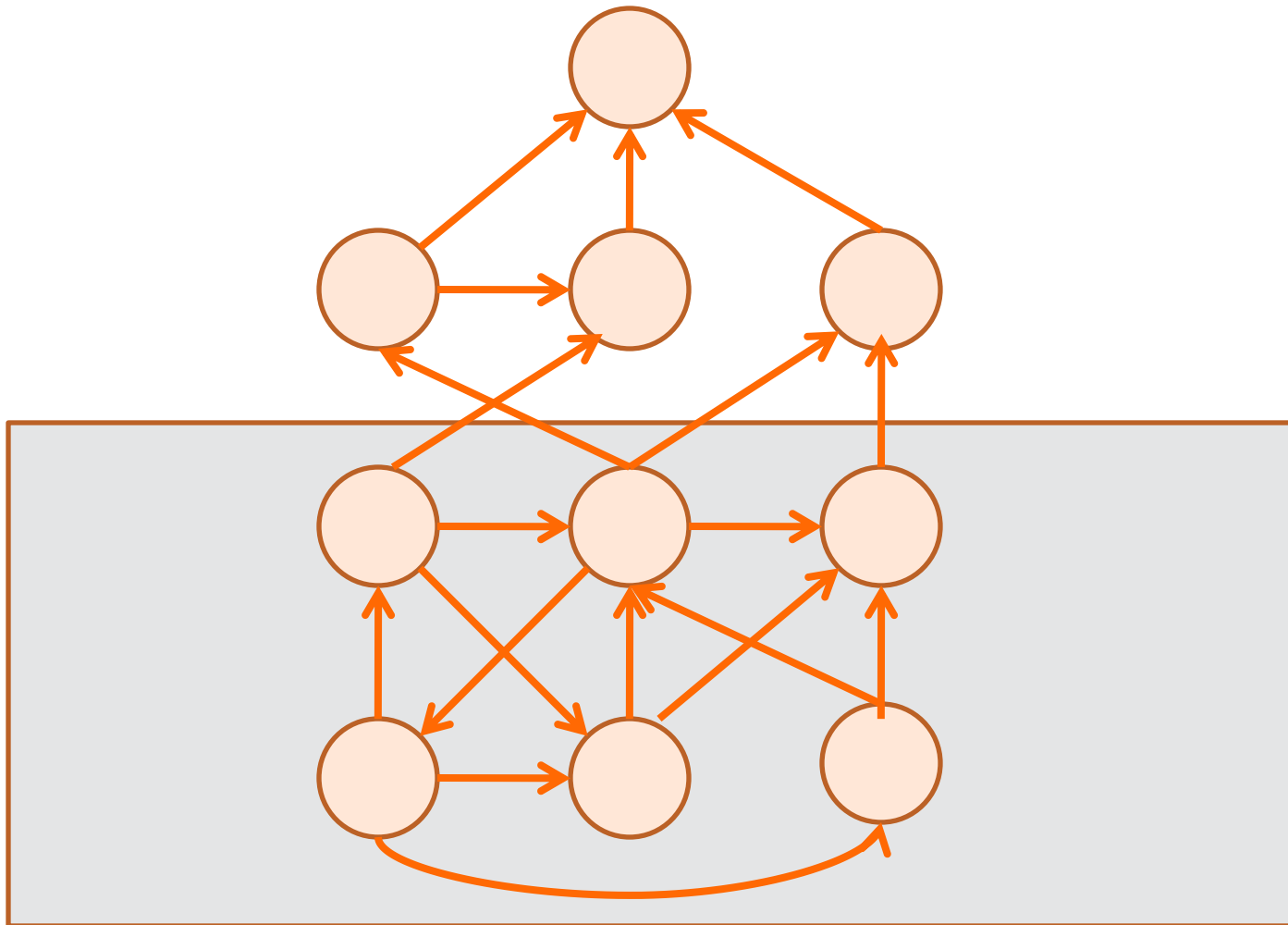
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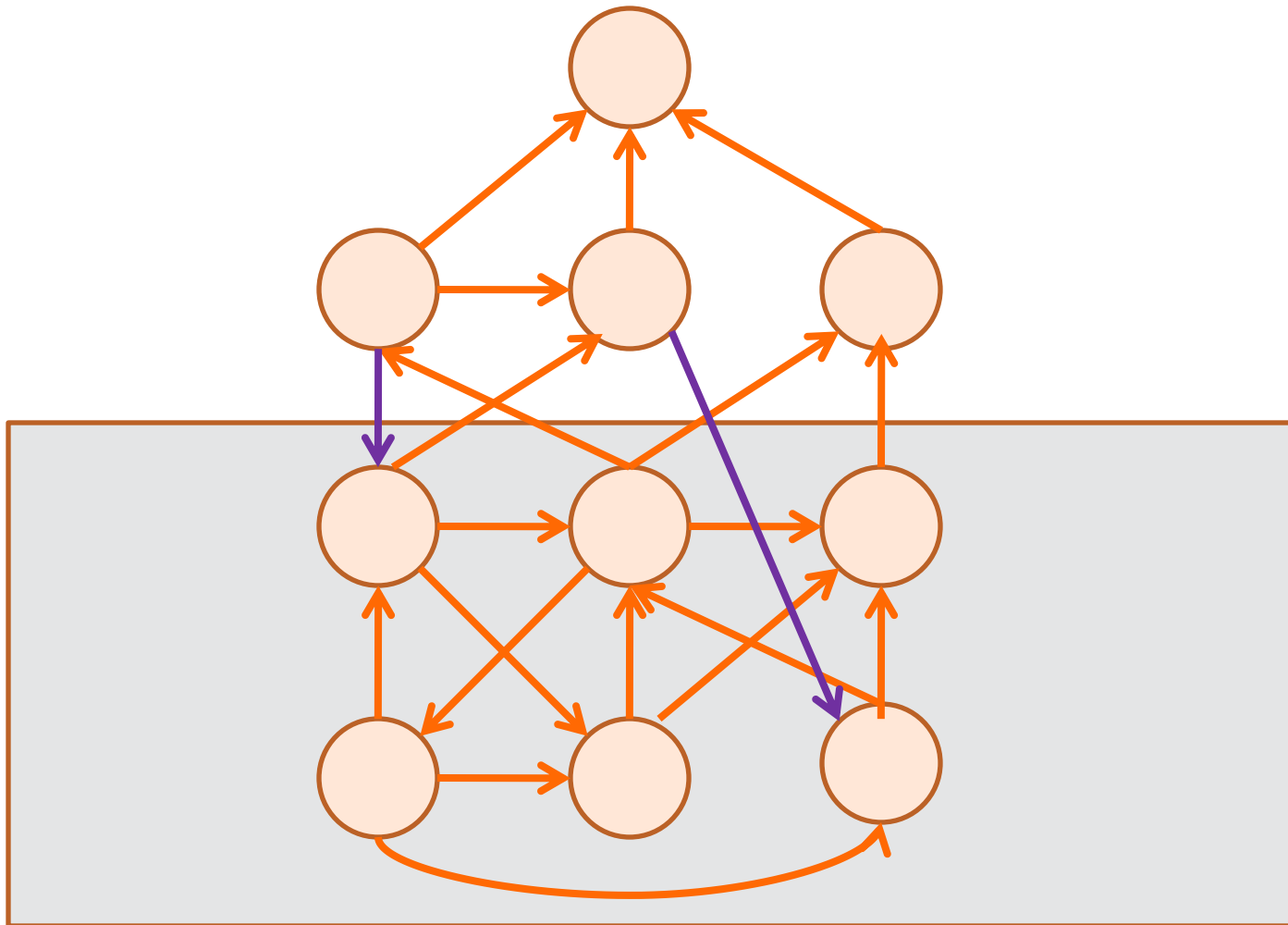
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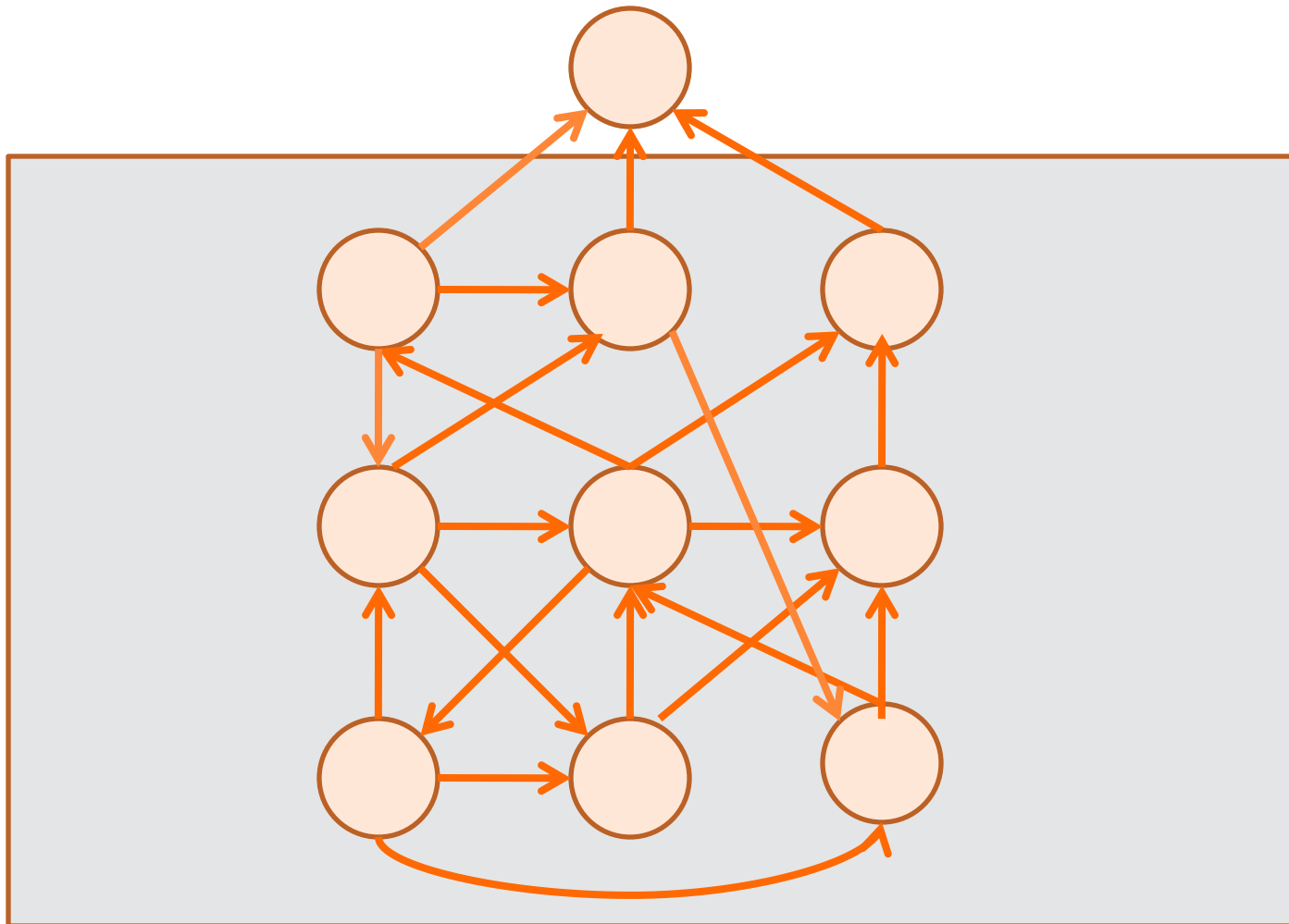
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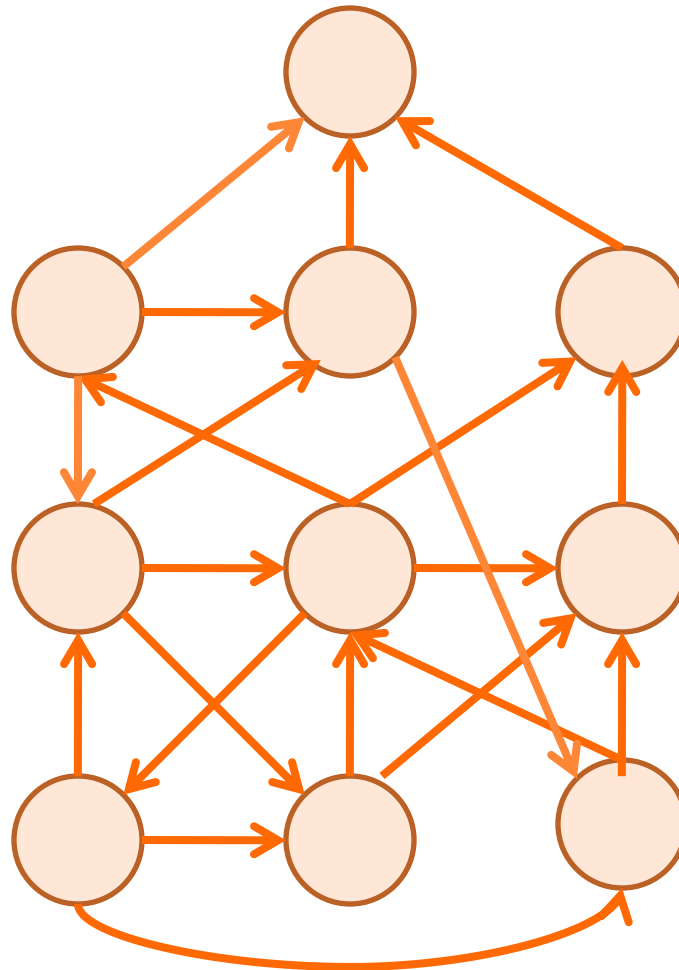
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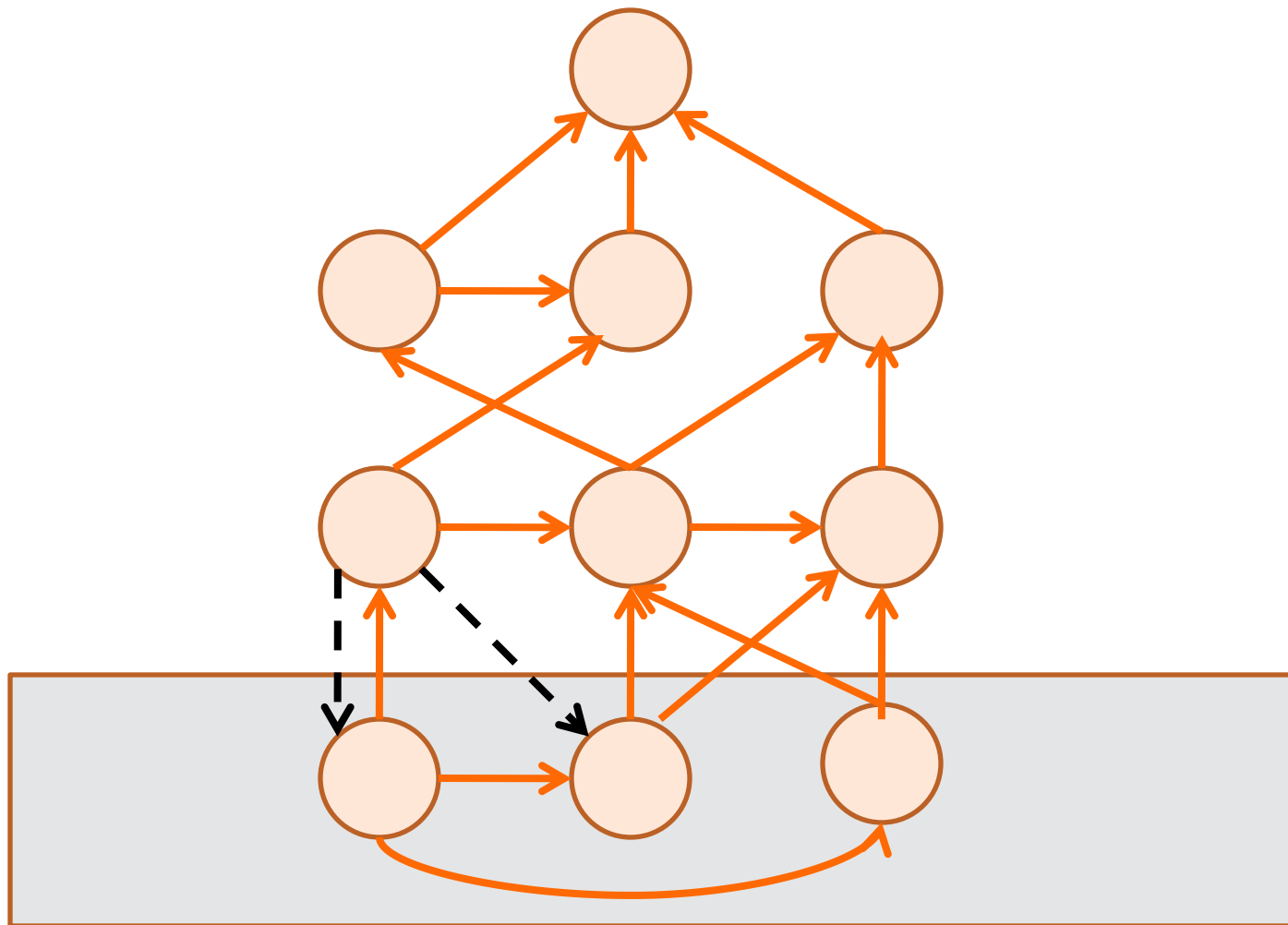
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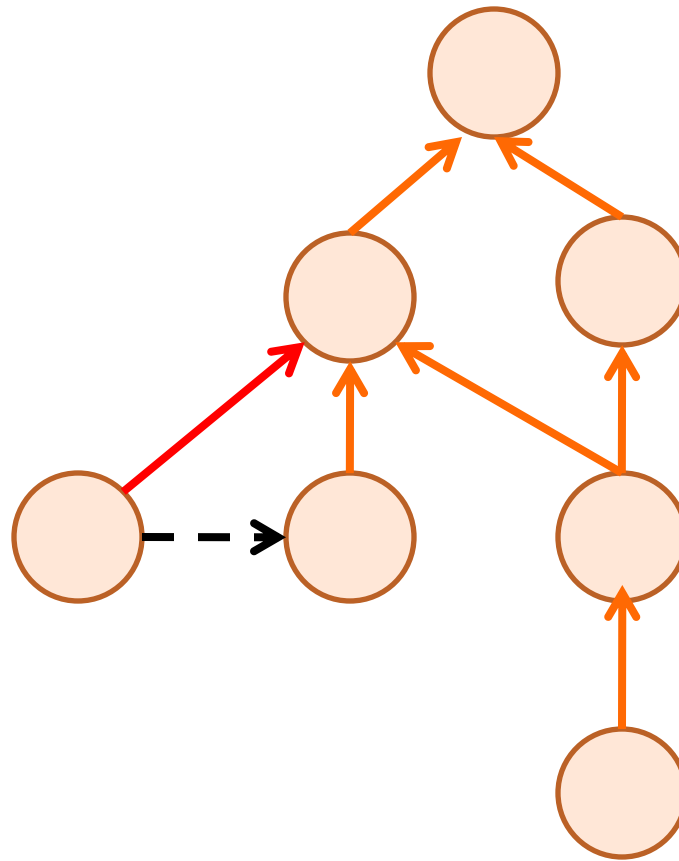
FIND-DOWN-EDGES

- For each node u at current level
 - Sort each node v_i in C (**complete set**) by distance to the root in $G - \{u\}$
 - Let $v_1 \dots v_k$ be the sorted v_i s
 - Let $pi_1 \dots pi_k$ be their corresponding shortest paths to the root in $G - \{u\}$
 - For i from 1 to k
 - Do experiment of firing u , leaving pi_i free, and suppressing the rest of the nodes.

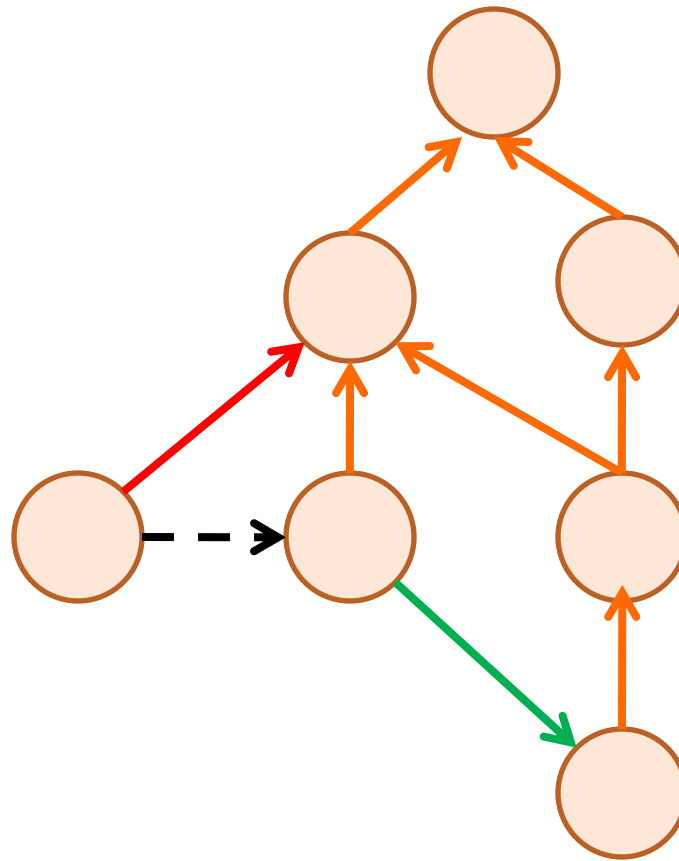
FOR EXAMPLE



WITH ONES – A PROBLEM



WITH ONES – A PROBLEM



WITH ONES

- Algorithm gets more complicated
- Level edges and down edges are found in one subroutine
- In looking for down edges from u , need to avoid not just u , but also all nodes reachable from u by 1 edges
- There always exists some pair of nodes, with source in L (current level) and destination in $C + L$ where you can look for an edge.

IN THE END

- We do 1 query per each possible edge, giving an $O(n^2)$ algorithm
- Matches the $\Omega(n^2)$ lower bound

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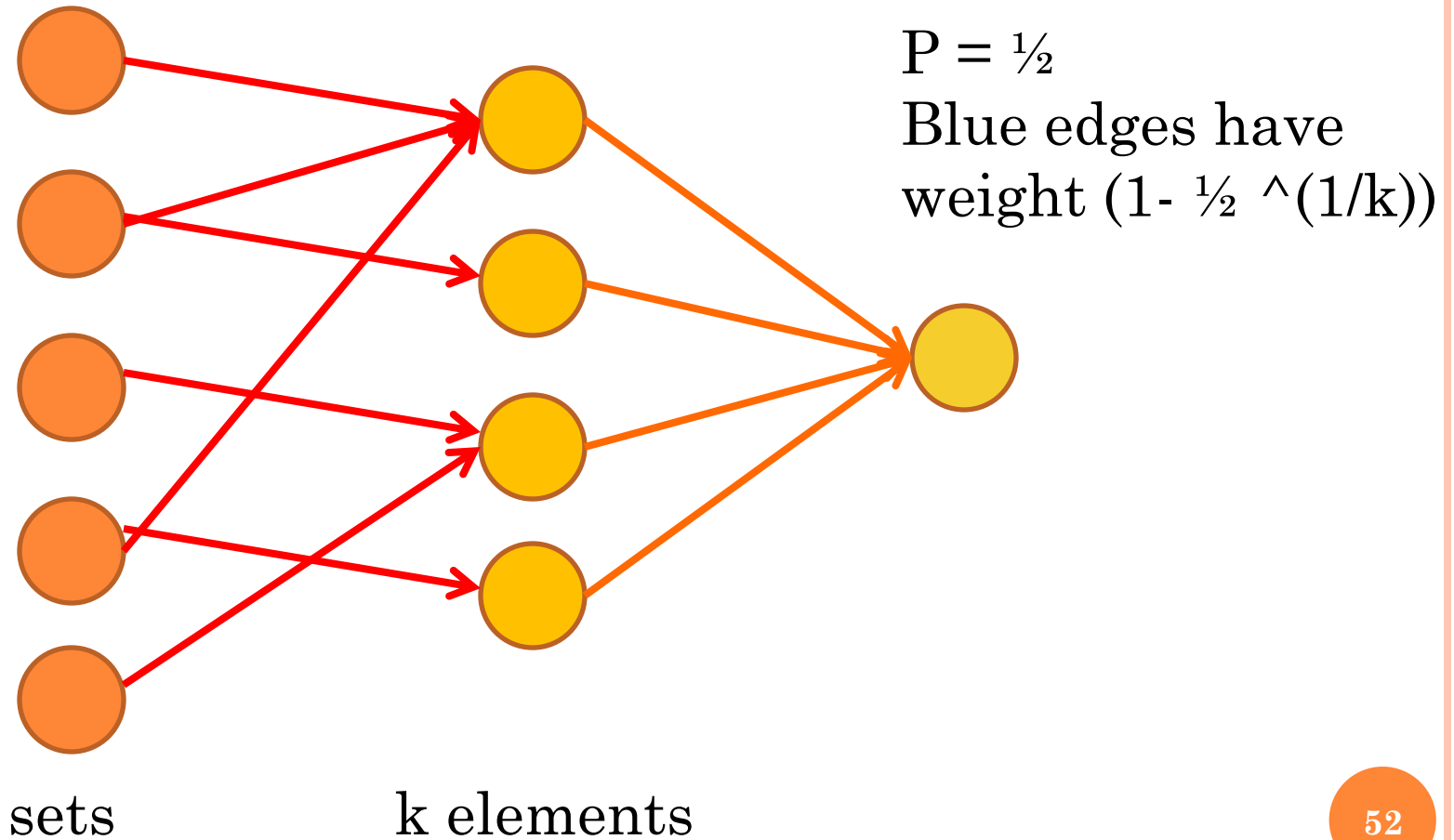
FINDING INFLUENTIAL NODES

- Suppose instead of learning the social network, we wanted to find an influential set of nodes quickly.
- A set of nodes is **influential** if, when activated, activates the output with probability at least p

FINDING INFLUENTIAL NODES

- Suppose instead of learning the social network, we wanted to find an influential set of nodes quickly.
- A set of nodes is **influential** if, when activated, activates the output with probability at least p
- NP Hard to Approximate to $\log n$, even if we know the structure of the network

REDUCTION FROM SET COVER



AN APPROXIMATION ALGORITHM

- Say the optimal solution has m nodes
- Suppose we wanted to **fire the output with probability $(p - \epsilon)$**
- Let I be the set of chosen influential nodes.
- Observation: at any point in the algorithm, **greedily** adding one more node w to I makes

$$S(e_{I \cup \{w\}}) \geq S(e_I) + \frac{p - S(e_I)}{m}$$

ANALYZING GREEDY

- Using a greedy algorithm, we let k be the number of rounds the algorithm is run

For

$$p \left(1 - \frac{1}{m}\right)^k < \epsilon$$

it suffices that

$$e^{-\frac{k}{m}} < \frac{\epsilon}{p}$$

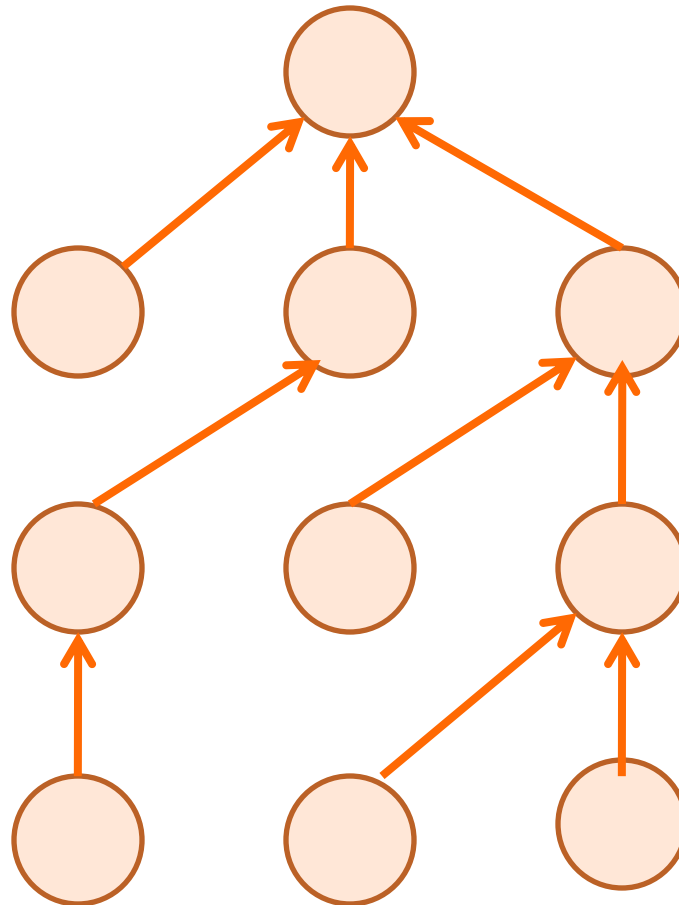
or

$$k > m \log \left(\frac{p}{\epsilon}\right).$$

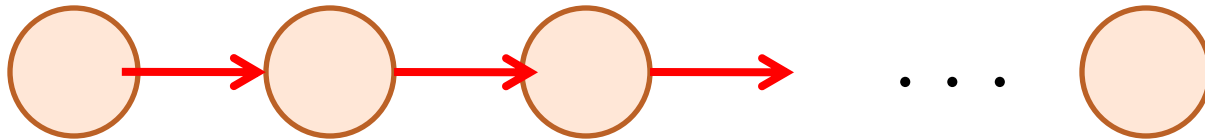
RECONCILING GREEDY

- Therefore after $m \log(p/\varepsilon)$ rounds, we get to within ε of p .
- To reconcile with the set cover reduction, if we set $\varepsilon = \frac{1}{2}^{1/n} - \frac{1}{2}^{1/(n-1)} = \theta(1/n^2)$, this forces us to cover all the elements.
- Giving a $m \log(p n^2) = O(m \log(n))$ approximation. Matches the set cover lower bound.

TREES



LOWER BOUND



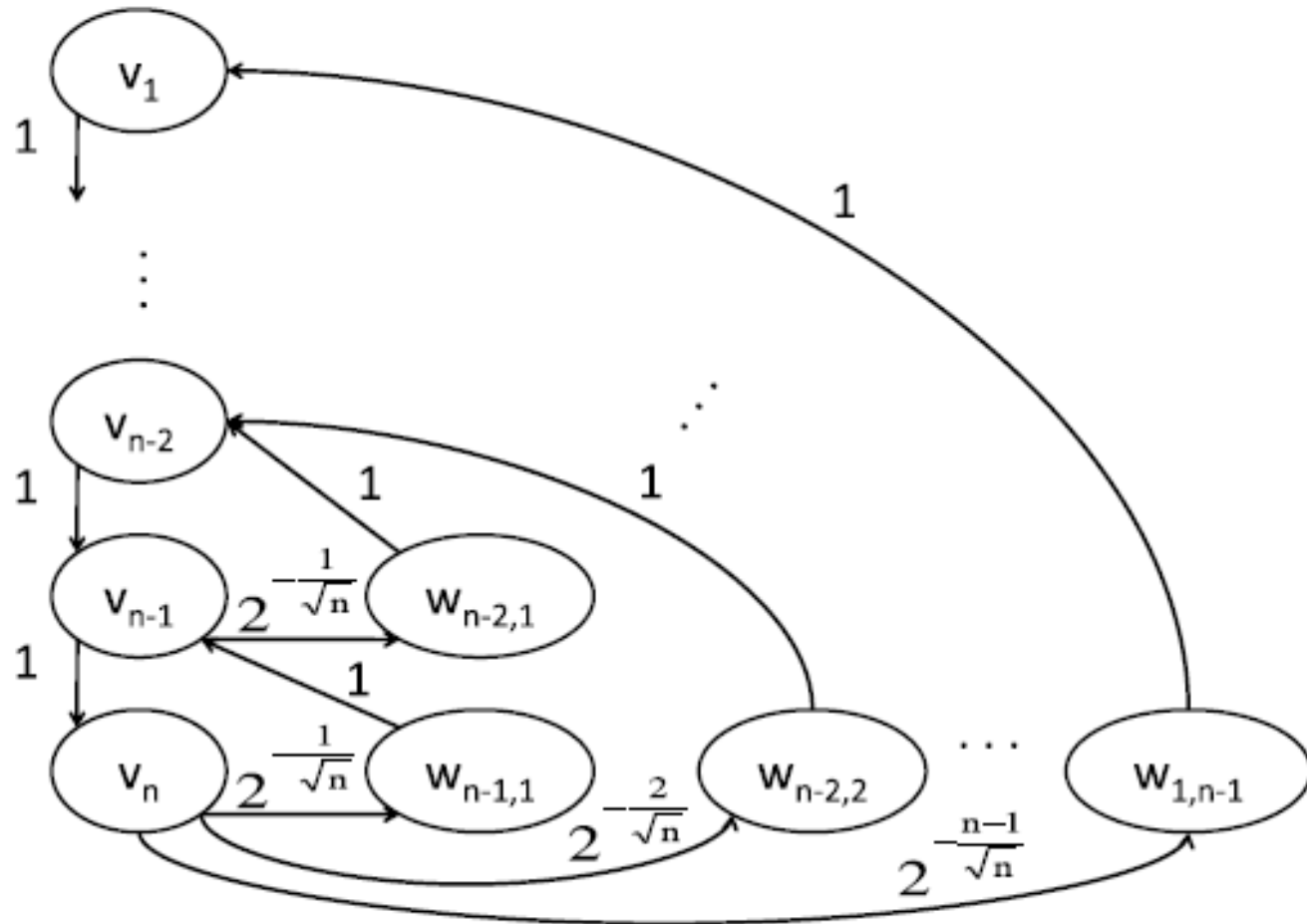
Like sorting with comparisons

Gives a $\Omega(n \log n)$ lower bound

THE IDEA FOR ALGORITHM

- **Ancestor Test.** To test if u has an ancestor in set S , fire u and suppress all nodes in S .
- We can build up a tree by adding one node at a time and binary searching where it belongs in the tree using ancestor tests.

IF WE DON'T HAVE EXACT VIQS



DISCUSSIONS AND OPEN PROBLEMS

- Interesting model to study various hidden structures.
- Finding non-path based methods for social networks. (Actually also an open question for learning circuits with VIQs)
- Reducing Query Size
- Other models.